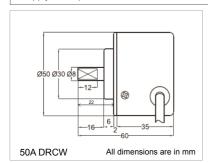
RotaCol® - Diamondline ANALOG CONTACTLESS ROTARY POSITION SENSOR CLAMPING FLANGE - 2 PRECISION BALL BEARINGS

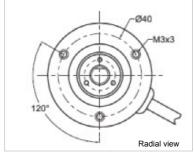
Heavy duty - Metalcase - 2 Ball bearings Hall effect magnetic

Output : 0 - 5V ratiometric, 0 - 5V, 0 - 10V, 4 - 20 mA, 0 - 20 mA 50 mm Ø robust metal aluminium housing with 2 ball bearings Clamping flange with 3 screws.

Shock & vibration proof, Measurement range 0° - 360°

1-Supply (Yellow) 2-Output (Brown) 3-Ground (White): For OCG, OCR 1-Supply; 2-Output; 3-Ground: For OCM, OCTA, OCTR





ELECTRICAL CHARACTERISTICS

111011100								
0 - 360°, any angle from 0 - 200 - 360								
programmable in steps of 1°								
ectrical speed (max.) 160 rpm (default) / 800 rpm (optional)								
4096 step (12 bit)								
Supply voltage								
5V ± 10%	0 - 5V (ratiometric)							
9 - 30V	0 - 5V							
15 - 30V	0 -10V							
15 - 30V	4 - 20 mA							
15 - 30V	0 - 20 mA							
	< 16 mA							
	± 0.5%							
	± 0.5 %							
	1 ms							
ERISTICS								
	360° (continuous)							
1S)	8 mm Ø X 22 mm							
	IP 54							
	0.05 Ncm							
	- 40 to +85° C							
	~ 75 million rotations							
	5000 rpm							
	250 gm							
3 c	ore round cable 2.5 mtr long							
а	nodized aluminium							
	stainless steel							
2 pı	ecision ball bearings							
	program 160 rpm (der 40 Supply voltage 5V ± 10% 9 - 30V 15 - 30V 15 - 30V 15 - 30V							

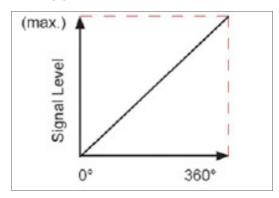


For full range of Rotary Sensor refer www.rotacol.info/rotamec.pdf

FUNCTION PRINCIPLE

The determination of angular position and signal generation is realised by an intelligent CMOS Hall sensor. A diametrical polarised magnet induces its magnetic field into the sensor. It rotates and provides a conditioned signal to the integrated electronic.

ANALOG INTERFACE



At the output of the sensor a variable voltage or variable current is provided proportional to the position of the shaft / axis over a complete angle range of 360 $^{\circ}$ or a subrange. The contactless sensor electronic guarantees a steady signal level and a very low linearity error of 0.5%. With supply voltages of 5VDC \pm 10% ; 9 - 30VDC ; 15 - 30V (24VDC) output signals of 0 - 5VDC; 0 -10VDC; 0 - 20mA ; 4 - 20mA at the sensor output are provided. Besides this a large variety of electrical options such as Zero point programming, Centre point programming, Multipoint programming, 2 Channel redundant outputs are provided. Other options on request.

Default version:

 360° CW Electrical & Mechanical angle, electrical speed 160 rpm, 3 Core round cable 2.5 mtr long

OR	RDERING INFORMATION Refer to electrical and mechanical options on page 2																		
Housing diameter	Analog output	Diamondline	RotaCol	Clamping flange with 3 screws	Signal	0 - 5V (ratiometric) 0 - 5V 0 - 10V 4 - 20mA 0 - 20mA	2 channel redundant output (only for voltage outputs)	Electrical angle	any angle from 0-20 to 0-360 programmable in steps of 1° (default 360°)	Direction of Rotation	Clockwise (CW)- (default) Counter clockwise (CCW)	Programming options for non - effective electrical angle (only if elec, angle is < 360°)	Delta 1/2 Low level High level Variable level	Programming options	Zero point Center point Multipoint	Special shaft length (default 22 mm FMS)	Special cable length - only for OCR, OCG (default 2.5 mtr long)	Output connections	3 Core round cable 2.5 mtr long (default) Miniature connector Cable gland with 2.5 mtr round cable Terminal block Axial Terminal block Radial
20	∢	٥	RC	>		\$0505 \$DC05 \$2410 \$2442 \$2420	2C		×	CW		PEX	PE1 PE2 PE3 PE4	POx	POZ POC POM	Axx	CVxx	OCXX	OCR OCM OCTA OCTA
50	A	D	RC	W		Sxxxx	2C		xxx	CW.	/ CCW		Ex		Ох	Axx	CVxx		OCxx

Example with description - **50A DRCW S2442 180CW PE1 POZ OCG -** 50mm diameter, analog output, Diamondline (Shaft 8 mm Ø), RotaCol, clamping flange with 3 screws, Signal - 4-20 mA, 180 angle and clockwise, Delta 1/2, Zero point, Cable gland with 2.5 mtr round cable

ELECTRICAL OPTIONS FOR ANALOG VERSION 50A DRCW

Non-effective Electrical Angle (PE1) - Delta 1/2

If the electrical effective angle is programmed smaller than 360°, the remaining electrical non-effective angle is divided in two equal parts: high level & low level (Delta 1/2)

Low level (PE2)

If the electrical effective angle is programmed smaller than 360°, after reaching the maximum, the signal level falls to low level.

High level (PE3)

If the elecrical angle is programmed smaller than 360°, the signal level remains high after reaching the full level.

Variable level (PE4)

If the electrical angle is programmed smaller than 360°, remaining electrical non effective angle can be divided into high and low level in any ratio according to customer request.

Direction of Rotation (CW/CCW)

By default the direction of rotation is clockwise (CW). With this option it is also possible to change the direction from clockwise(CW) to counterclockwise (CCW).

Zero point Programming (POZ)

Mechanical zero point is aligned with marking on the sensor housing. Electrical zero point can be aligned to mechanical zero point. Zero point can be programmed at any offset.

Center Point Programming (POC)

Effective electrical angle is aligned with the mechanical zero point in such a way that equal effective angles in both rotating directions are achieved. Center point can be programmed at any offset.

Multi Point Programming (POM)

Output characteristics: 3 to 6 rising or falling linear segments. Min and max signal level can be defined within the total electrical angle. First and last linear segment (min/max) is always horizontal.1 to 3 setable calibration points.

2 Channel Redundant Output (2C)

This is realized by a Hall sensor chip consisting of 2 galvanically seperated sensing elements. One magnet provides a magnetic field simultaneously for both elements. Both elements can be programmed identically, or channel 2 can also be programmed independently from channel 1. (Valid only for 0505, DC05, and 2410 outputs).

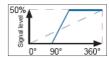
max. 19 0 360°

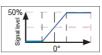


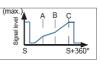














MECHANICAL OPTIONS FOR ANALOG VERSION 50A DRCW

Type / Series	Standard mechanical options	Customized mechanical options				
50A DRCW	Cable gland (OCG) ; Terminal Block (OCTA / OCTR) ; Miniature connector (OCM)	Special shaft length ; Special cable				

INTERCONNECTIONS

Standard Interconnections - 3 core round cable 2.5 mtr long - radial

Other Interconnection options

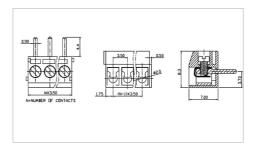
Cable gland (OCG)

Miniature connector (OCM)

3 core cable 2.5 mtr long 3 pin in integrated socket with plug

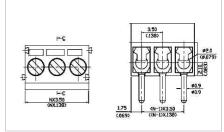
16 3 Terminal block - Axial (OCTA)
Wires leaving axial to shaft axis

3 sockets



Terminal block - Radial (OCTR) Wires leaving radial to shaft axis

3 sockets



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